

Reg. No.

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**B.E./ B.TECH. DEGREE EXAMINATIONS, MAY 2024**

Second Semester

**EE22251 – BASIC ELECTRICAL AND ELECTRONICS ENGINEERING FOR CHEMICAL ENGINEERS***(Chemical Engineering)***(Regulation 2022)****TIME:3 HOURS****MAX. MARKS: 100**

COURSE OUTCOMES	STATEMENT	RBT LEVEL
CO 1	Apply basic electrical laws for the electrical circuits and understand sensors and measurement principles	3
CO 2	Analyze the characteristics of various semiconductor devices and develop circuits for an application.	4
CO 3	Analyze and select electrical machines for drive applications based on characteristics.	4
CO 4	Identify the structure and types of Electrical drives for specific applications.	3
CO 5	Apply control methods for Electrical Machine and Drives in chemical process industries	3

**PART- A(20x2=40Marks)**

(Answer all Questions)

QUESTION	CO	RBT LEVEL
1. State the laws which are used to find unknown currents and voltages in a circuit.	1	2
2. Calculate the total resistance of the circuit.	1	3

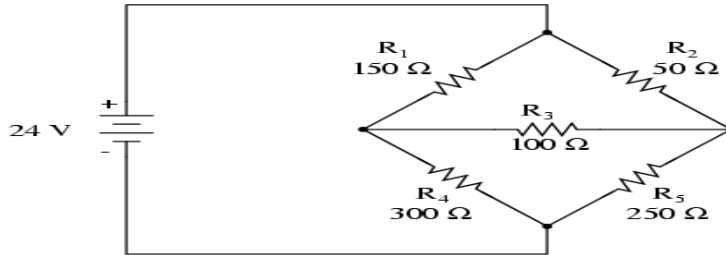
3. Contrast the lead-lag behaviour of current waveform with respect to voltage waveform in each of R, L and C circuits.	1	3
4. What are the factors affecting resistance?	1	2
5. Differentiate between zener breakdown and avalanche breakdown.	2	2
6. Draw V-I characteristics of SCR.	2	2
7. Why IGBT is very popular nowadays?	2	3
8. What is meant by step-up and step-down chopper?	2	2
9. Write the voltage equation of DC motor and DC generator.	3	2
10. Clarify why brushes in a generator are made of carbon?	3	2
11. Draw the speed torque characteristics of (a) Constant Torque type load    (b) Generator type load (c) Fan type load    (d) constant power type load.	3	3
12. What is the Necessity of starter?	3	2
13. List the factors affecting the selection of electric drives.	4	2
14. Mention the function of Power modulator.	4	2
15. Give the formula for computing power requirement for a liner movement.	4	2

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|-----|---|---|---|
| 16. | What is meant by multimotor drive? Give an example.                               | 4 | 2 |
| 17. | Compare the chopper control and phase control schemes for <u>DC motor</u> drives. | 5 | 2 |
| 18. | Mention the different methods of speed control employed for DC Motor.             | 5 | 2 |
| 19. | List the different methods of speed control of three phase induction motor.       | 5 | 2 |
| 20. | What is the need for PWM inverter control?  | 5 | 3 |

**PART- B (5x 10=50Marks)**

<b>Marks</b>	<b>CO</b>	<b>RBT LEVEL</b>
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|----------------|---|-------------|----------|----------|
| <b>21. (a)</b> | Determine the mesh and branch currents for the following Network is shown in figure | <b>(10)</b> | <b>1</b> | <b>3</b> |
|----------------|---|-------------|----------|----------|



**(OR)**

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|----------------|---|-------------|----------|----------|
| <b>(b)</b>     | Explain in detail about Resistance Temperature Detector and its characteristics.                      | <b>(10)</b> | <b>1</b> | <b>3</b> |
| <b>22. (a)</b> | Describe the working of a PN junction diode with neat diagrams. Also explain its V-I characteristics. | <b>(10)</b> | <b>2</b> | <b>3</b> |
|                | <b>(OR)</b>   |             |          |          |
| <b>(b)</b>     | Draw and explain working of full bridge rectifier.  | <b>(10)</b> | <b>2</b> | <b>3</b> |
| <b>23. (a)</b> | Explain about the speed-torque characteristics of a DC Shunt Motor with suitable graph and equations. | <b>(10)</b> | <b>3</b> | <b>3</b> |
|                | <b>(OR)</b>   |             |          |          |
| <b>(b)</b>     | State the various starting methods of squirrel cage induction motor. Explain any two of them.         | <b>(10)</b> | <b>3</b> | <b>3</b> |
| <b>24. (a)</b> | Derive the expression for the heating time constant and draw the heating and cooling curve.           | <b>(10)</b> | <b>4</b> | <b>3</b> |
|                | <b>(OR)</b>   |             |          |          |
| <b>(b)</b>     | Explain the different classes of duties of a motor with neat sketch.                                  | <b>(10)</b> | <b>4</b> | <b>3</b> |
| <b>25. (a)</b> | Explain the field control method used for D.C series motor for speed control?                         | <b>(10)</b> | <b>5</b> | <b>3</b> |
|                | <b>(OR)</b>   |             |          |          |
| <b>(b)</b>     | What is meant by slip power recovery scheme? Explain with the necessary diagram.                      | <b>(10)</b> | <b>5</b> | <b>3</b> |

**PART- C (1x 10=10Marks)**

(Q.No.26 is compulsory)

<b>Marks</b>	<b>CO</b>	<b>RBT LEVEL</b>
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|------------|---|-------------|----------|----------|
| <b>26.</b> | Explain how an DC Shunt motor is brought to stop by (i) Plugging and (ii) dynamic braking. Explain the conditions to achieve electric regenerative braking. | <b>(10)</b> | <b>3</b> | <b>4</b> |
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